

#### Key ideas, terms & concepts in SEM

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## Plan

- Path diagrams
- Exogenous, endogenous variables
- Variance/covariance matrices
- Maximum likelihood estimation
- Parameter constraints
- Nested Models and Model fit
- Model identification

# Path diagrams

 An appealing feature of SEM is representation of equations diagrammatically

e.g. bivariate regression Y= bX + e



# Path Diagram conventions

Measured latent variable



Observed / manifest variable

Error variance / disturbance term



Covariance / non-directional path

#### Regression / directional path

## Reading path diagrams



With 3 error variances

Causes/measured by 3 observed variables

A latent variable

#### Reading path diagrams



2 latent variables, each measured by 3 observed variables

## Reading path diagrams



2 latent variables, each measured by 3 observed variables

Error/disturbance

#### Exogenous/Endogenous variables

- Endogenous (dependent)
  - caused by variables in the system
- Exogenous (independent)
  - caused by variables outside the system
- In SEM a variable can be a predictor <u>and</u> an outcome (a mediating variable)

#### 2 (correlated) exogenous variables



#### $\eta$ 1 endogenous, $\eta$ 2 exogenous



#### Data for SEM

- In SEM we analyse the variance/covariance matrix (S) of the observed variables, not raw data
- Some SEMs also analyse means
- The goal is to summarise S by specifying a simpler underlying structure: the SEM
- The SEM yields an implied var/covar matrix which can be compared to S

#### Variance/Covariance Matrix (S)

	x1	x2	x3	x4	x5	X6
x1	0.91	-0.37	0.05	0.04	0.34	0.31
x2	-0.37	1.01	0.11	0.03	-0.22	-0.23
x3	0.05	0.11	0.84	0.29	0.14	0.11
x4	0.04	0.03	0.29	1.13	0.11	0.06
x5	0.34	-0.22	0.14	0.11	1.12	0.34
x6	0.31	-0.23	0.11	0.06	0.34	0.96

# Maximum Likelihood (ML)

- ML estimates model parameters by maximising the Likelihood, L, of sample data
- L is a mathematical function based on joint probability of continuous sample observations
- ML is asymptotically unbiased and efficient, assuming multivariate normal data
- The (log)likelihood of a model can be used to test fit against more/less restrictive baseline

#### Parameter constraints

- An important part of SEM is fixing or constraining model parameters
- We fix some model parameters to particular values, commonly 0, or 1
- We constrain other model parameters to be equal to other model parameters
- Parameter constraints are important for identification

#### Nested Models

• Two models, A & B, are said to be 'nested' when one is a subset of the other

(A = B + parameter restrictions)

e.g. Model B:

 $y_i = a + b_1 X_1 + b_2 X_2 + e_i$ 

• Model A:

 $y_i = a + b_1 X_1 + b_2 X_2 + e_i$  (constraint:  $b_1 = b_2$ )

• Model C (not nested in B):  $y_i = a + b_1X_1 + b_2Z_2 + e_i$ 

# Model Fit

- Based on (log)likelihood of model(s)
- Where model A is nested in model B: LLA-LLB = $\chi^2$ , with df = dfA-dfB
- Where p of > 0.05, we prefer the more parsimonious model, A  $\chi^2$
- Where B = observed matrix, there is no difference between observed and implied
- Model 'fits'!

#### Model Identification

 An equation needs enough 'known' pieces of information to produce unique estimates of 'unknown' parameters

X + 2Y=7 (unidentified)

3 + 2Y=7 (identified) (y=2)

- In SEM 'knowns' are the variances/ covariances/ means of observed variables
- Unknowns are the model parameters to be estimated

### Identification Status

- Models can be:
  - Unidentified, knowns < unknowns</p>
  - Just identified, knowns = unknowns

– Over-identified, knowns > unknowns

- In general, for CFA/SEM we require overidentified models
- Over-identified SEMs yield a likelihood value which can be used to assess model fit

# Assessing identification status

- Checking identification status using the counting rule
- Let s = number of observed variables in the model
- number of non-redundant parameters =  $\frac{1}{2}s(s+1)$
- t=number of parameters to be estimated  $t > \frac{1}{2}s(s+1)$  model is unidentified

$$t < \frac{1}{2}s(s+1)$$
 model is over-identified

## Example I - identification



**Non-redundant parameters** 

$$\frac{1}{2}s(s+1) = 6$$

#### parameters to be estimated

- 3 \* error variance +
- 2 \* factor loading +
- 1 \* latent variance = 6

6 - 6 = 0 degrees of freedom, model is just-identified

# Controlling Identification

- We can make an under/just identified model over-identified by:
  - Adding more knowns
  - Removing unknowns
- Including more observed variables can add more knowns
- Parameter constraints remove unknowns
- Constraint b<sub>1</sub>=b<sub>2</sub> removes one unknown from the model (gain 1 df)

#### Example 2 – add knowns



**Non-redundant parameters** 

$$\frac{1}{2}s(s+1) = 10$$

#### parameters to be estimated

- 4 \* error variance +
- 3 \* factor loading +
- 1 \* latent variance = 8

10 - 8 = 2 degrees of freedom, model is **over-identified** 

#### Example 3 – remove unknowns

Constrain factor loadings = 1



#### **Non-redundant parameters**

$$\frac{1}{2}s(s+1) = \mathbf{6}$$

#### parameters to be estimated

- 3 \* error variance +
- 0 \* factor loading +
- 1 \* latent variance = 4

6 - 4 = 2 degrees of freedom, model is **over-identified** 

# Summary

- SEM requires understanding of some ideas which are unfamiliar for many substantive researchers:
  - Path diagrams
  - Analysing variance/covariance matrix
  - ML estimation
  - global 'test' of model fit
  - Nested models
  - Identification
  - Parameter constraints/restrictions





# For more information contact ncrm.ac.uk